

Probability and Statistics Review

random experiment: a process leading to at least two possible outcomes with uncertainty as to which will occur.

basic outcomes: possible outcomes of a random experiment

sample space: the set of **all** possible outcomes

event: a set of basic outcomes from the sample space; it **occurs** if the random experiment gives rise to one of its basic outcomes.

intersection: for two events A and B in the sample space S , their **intersection**, denoted $A \cap B$ is the set of all basic outcomes in S that belong to both A and B .

more generally, for K events E_1, E_2, \dots, E_K , their intersection

$E_1 \cap E_2 \dots \cap E_K$ is the set of all basic outcomes that belong to every E_i ($i = 1, 2, \dots, K$).

if the events A and B have no basic outcomes, they are called **mutually exclusive** and their intersection is said to be the **empty(null) set**.

for K events, they are said to be mutually exclusive if every pair of them is mutually exclusive.

union: for two events A, B in the sample space S , their **union**, denoted $A \cup B$ is the set of all basic outcomes in S that belong to at least one of these events.

more generally, for the K events E_1, E_2, \dots, E_K , their union, $E_1 \cup E_2 \dots \cup E_K$ is the set of all basic outcomes belonging to at least one of these events.

if these K events in the sample space S satisfy $E_1 \cup E_2 \dots E_K = S$, the K events are said to be **collectively exhaustive**.

complement: for an event A in the sample space S , the **complement** of A , denoted by \overline{A} is the set of basic outcomes of a random experiment belonging to S but not in A .

Probability Postulates:

1. for any event A in the sample space S $0 \leq P(A) \leq 1$
2. let A denote an event, and let O_i denote the basic outcomes. Then,
$$P(A) = \sum_A P(O_i)$$
3. $P(S) = 1$

Probability Rules

let A be an event in the sample space S . then

$$P(\bar{A}) = 1 - P(A)$$

decomposition rule:

$$P(B) = P(A \cap B) + P(\bar{A} \cap B)$$

since $A, (\bar{A} \cap B)$ are mutually exclusive, and their union is $A \cup B$, we get the **addition rule**:

$$P(A \cup B) = P(A) + P(B) - P(A \cap B)$$

Conditioning on Information

the chance a particular event **will** occur is often likely to depend on whether or not some other event(s) **have** occurred.

we'll approach this issue through the notion of **conditional probability**.

Specifically, let A and B be two events in the sample space S . The **conditional probability** of event A given event B , denoted by $P(A | B)$, is defined as :

$$P(A | B) = \frac{P(A \cap B)}{P(B)}$$

provided that $P(B) > 0$. Similarly,

$$P(B | A) = \frac{P(A \cap B)}{P(A)}$$

multiplication rules:

for two events A, B in the sample space S , the probability of their intersection is :

$$P(A \cap B) = P(A | B)P(B)$$

and

$$P(A \cap B) = P(B | A)P(A)$$

Statistical Independence

Two events A, B in the sample space S said to be **statistically independent** if

$$P(A \cap B) = P(A)P(B)$$

or, by the multiplication rules

$$P(A | B) = P(A) \quad \text{if} \quad P(B) > 0$$

$$P(B | A) = P(B) \quad \text{if} \quad P(A) > 0$$

in general, the events E_1, E_2, \dots, E_K are statistically independent if

$$P(E_1 \cap E_2 \cap \dots \cap E_K) = P(E_1)P(E_2) \cdots P(E_K)$$

Bayes theorem

fundamental law for revising probabilities given new information.

recall the multiplication rules of probability:

$$P(A \cap B) = P(A | B)P(B)$$

$$P(A \cap B) = P(B | A)P(A)$$

equating these two gives:

$$P(B | A) = \frac{P(A | B)P(B)}{P(A)}$$

can interpret this in terms of subjective definition of probability. Suppose individual is interested in event B and assigns a subjective probability $P(B)$. This is called a **prior** probability.

With additional information, say the occurrence of the event A , the probability assigned to event B may be modified. This new probability is called the **posterior** probability.

Bayes' Theorem is thus a mechanism for updating a prior probability to a posterior probability when additional information becomes available.

Bayes theorem can be generalized to K events in the following way. Suppose E_1, E_2, \dots, E_K are mutually exclusive and collectively exhaustive events, and let A be some other event.

Suppose for some i we want $P(E_i | A)$. This can be evaluated with the previous formula, but the denominator can be expressed differently.

Recall that:

$$P(A) = P(E_1 \cap A) + P(E_2 \cap A) + \dots + P(E_K \cap A)$$

and the multiplication rule:

$$P(E_j \cap A) = P(A | E_j)P(E_j) \quad (j = 1, 2, \dots, K)$$

we thus get :

$$P(A) = P(A | E_1)P(E_1) + P(A | E_2)P(E_2) + \dots P(A | E_K)P(E_K)$$

Thus we can restate Bayes Theorem as :

$$P(E_i | A) = \frac{P(A | E_i)P(E_i)}{P(A | E_1)P(E_1) + \dots P(A | E_K)P(E_K)}$$

e.g. Test for type of cancer.

$$P(+ | C) = 0.95 \quad P(- | C) = 0.05$$

$$P(+ | C^c) = 0.05 \quad P(- | C^c) = 0.95$$

$$P(C) = 0.00001$$

Is this a good test?

$$P(C | +) = \frac{0.95 * 0.00001}{0.95 * 0.00001 + 0.05 * 0.99999} = 1.9 * 10^{-4}$$

Random Variables

a **random variable** is a variable that takes on numerical values determined by the outcome of a random experiment.

notationally, we will let capital letters denote (X) denote the random variable and the corresponding lowercase (x) denote the possible values it can take.

we classify random variables with respect to how many values they can take:

a random variable is **discrete** if it can take on no more than a countable number of values.

a random variable is **continuous** if it can take any value in an interval.

Probability Distributions for Discrete Random Variables

the **probability distribution** of a random variable is any representation of the probabilities of all the possible outcomes.

the **probability function**, or **probability mass function**, denoted by

$P_X(x)$, of a discrete random variable X , expresses the probability that X takes the value x as a function of x :

$$P_X(x) = P(X = x)$$

Properties of Probability Functions

1. $P_X(x) \geq 0$ for all values of x .

2.
$$\sum_x P_X(x) = 1$$